

**ACAI'2001 & EASSS'2001**

**Prague  
6 July 2001**

**Multi-Agent Oriented  
Methodology  
And Programming**

**(provisional set of slides)**

**Yves Demazeau**  
Yves.Demazeau@imag.fr

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**LECTURE CONTENTS**

**Introduction**  
**Analysis and Design**  
**Models**  
**Development**  
**Deployment**  
**Methodology**  
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**Conclusion**

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## INTRODUCTION

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## What is an Agent ?

**External Definition** : a **real** or **virtual** entity that evolves in an **environment**, that is able to **perceive** this environment, that is able to **act** in this environment, that is able to **communicate** with other agents, and that **exhibits** an **autonomous** behaviour

---> **autonomous agents**

---> **the autonomy principle**

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## What is an Agent ?

**External Definition :** a **real** or **virtual** entity that evolves in an **environment**, that is able to **perceive** this environment, that is able to **act** in this environment, that is able to **communicate** with other agents, and that **exhibits** an **autonomous** behaviour

---> the **autonomy principle**

**Internal Definition :** a **real** or **virtual** entity that **encompasses** some **local control** in some of its **perception** , **communication** , **knowledge acquisition** , **reasoning** , **decision** , **execution**, **action** processes.

---> the **delegation principle**

---> **personal assistants, mobile objects, AI systems**

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## What is a Multi-Agent System ?

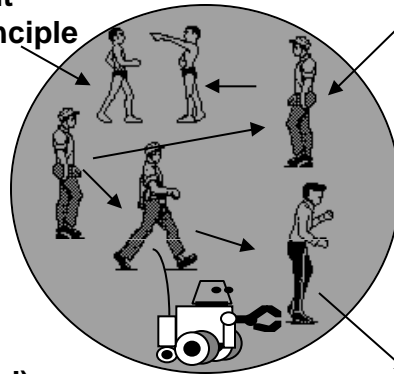
A **set** of possibly organized agents which interact in a **common environment**

---> the **distribution principle**

**MAS main interests :**

---> To extend classical mono-agent AI models and tools (**A-centered**)

---> To study specific multi-agent models and tools (**MAS-centered**)



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## Agents and Multi-Agent Systems

**External Definition** : a **real** or **virtual** entity that evolves in an **environment**, that is able to **perceive** this environment, that is able to **act** in this environment, that is able to **communicate** with other agents, and that **exhibits** an **autonomous** behaviour

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**Internal Definition** : a **real** or **virtual** entity that **encompasses** some **local control** in some of its **perception** , **communication** , **knowledge acquisition** , **reasoning** , **decision** , **execution** , **action** processes.

---> the **delegation principle**

**But there is no agent without multi-agent systems !**

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## Agents Environments Interactions Organisations

### Agents

- internal architectures of the processing entities

### Environment

- domain-dependent elements for structuring external interactions between entities

### Interactions

- elements for structuring internal interactions between entities

### Organisations

- elements for structuring sets of entities within the MAS

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## Distributed Problem Solving

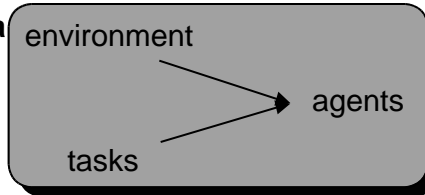
**global conceptual model**

**global problem**

**global success criteria**

**division of :**

knowledge  
resources  
control  
authority



**focus on the collaborative resolution of global problems by a set of distributive entities**

society goals directed  
input : tasks, environment  
output : model of the distributed entities  
schema to solve the tasks

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## Decentralized System Simulation

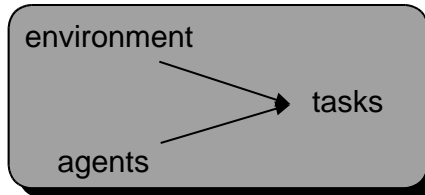
**local conceptual models**

**local problems**

**local success criteria**

**division of :**

knowledge  
resources  
control  
authority



**focus on the coordinated activities of a set of agents evolving in a multi-agent world**

agent goals directed  
input : agents, environment  
output : tasks which can be solved  
schema to solve the tasks

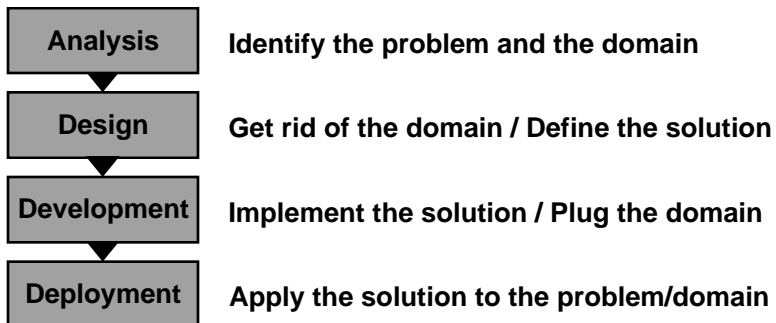
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## MAS Methodology

### Methodology

= Approach + Model + Tools + Problem + Domain  
= Analysis + Design + Development + Deployment



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## MAS Applications

Computer-Aided Design  
Computer Vision  
Decision Support  
Electronic Commerce  
Enterprise Modelling  
Manufacturing Systems  
Natural Language Processing  
Network Monitoring  
Office and Home Automation  
Robotics Control  
Societies Simulation  
Spatial Data Handling  
Telecommunication Routing  
Traffic Management

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## **ANALYSIS AND DESIGN**

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## **SATURNE : Origin of the studies**

**Building, maintaining, using a world description  
from data issued by several sensors  
Building an open, domain-independent system**

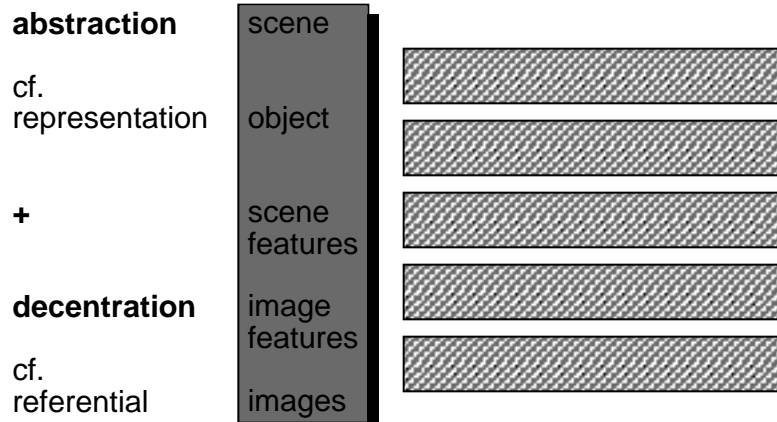
- Decomposing the knowledge representation problem into level-agents (cf. abstraction, decentration)
- Decomposing the knowledge processing problem into focus-agents (cf. focalisation / characteristics)
- Intersecting the level-agents and the focus-agents into basic agents
- Two behaviours to be exhibited by the society :

**---> modelling : scene understanding  
---> interpreting : recognition and localisation**

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## SATURNE : Horizontal levels of representation



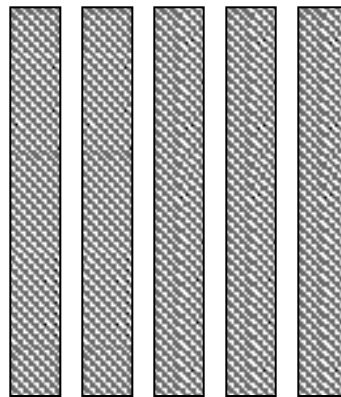
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## SATURNE : Vertical foci of attention

**explicitly designed**  
cf. characteristics

contours  
highlights  
range data  
stereo vision  
regions  
...



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## SATURNE : Agents and Society of Agents

### organisational structure

horizontal links  
vertical links

**basic agents**

### interaction media

**between foci agents**

levels of representation

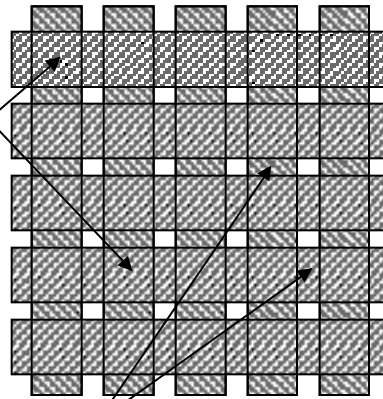
**between level agents**

foci of attention

**between basic agents**

levels of representation

x foci of attention



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## SATURNE Behaviour : Scene Understanding

### input

image  
(environment)  
basic agents

### output

scene understanding  
(global goals)

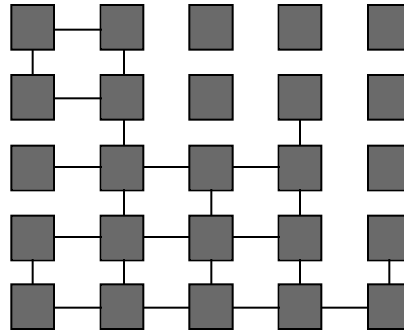
### data driven

no explicit goal

no centralised representation

information exchange towards local coherence

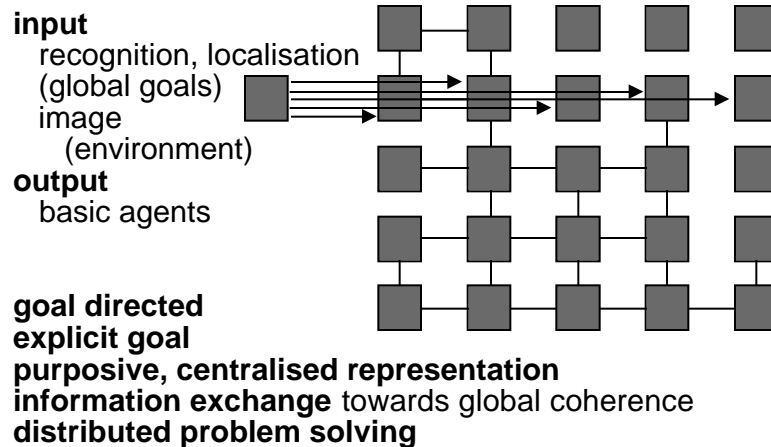
decentralized system simulation



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## SATURNE Behaviour : Recognition Localisation



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## The COHIA (or KR x KP) Approach

### Structuring the knowledge representation

- criteria : abstraction and decentration
- horizontal decoupling levels of representation
- vertical first-hand **interactions** : perception

### Structuring the knowledge processing

- criteria : foci on space, time, features, models, tasks
- vertical decoupling into foci of attention
- horizontal second-hand **interactions** : communication

### Identifying the basic entities of the system

- definition : intersection of level-agents & focus-agents
- choices : **agents, organisation, environment** models

### Identifying the behaviour of the system

- System simulation : driven by the nature of the agents
- Problem solving : guided by the goals of the society

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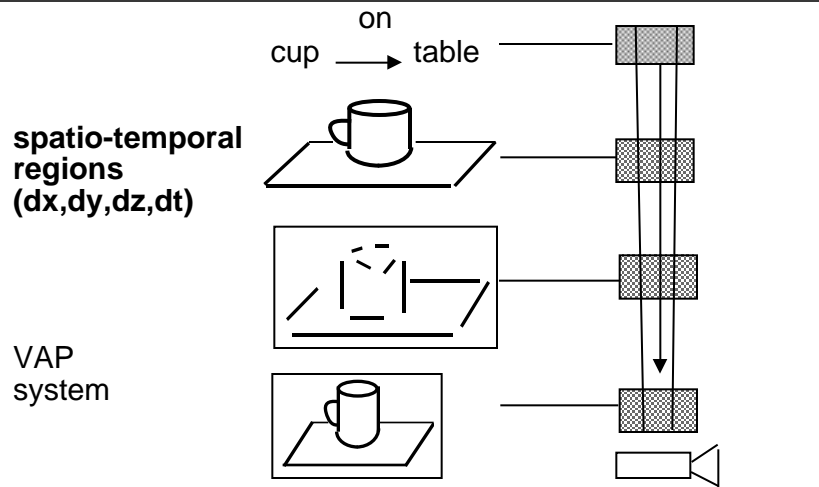
### Decomposition by Abstraction [Demazeau 86]

	scene	scene	interpretation
3D model	object	feature grouping	recognized objects
2,5D model	scene features	scene description	scene elements
primal sketch	image features	image description	image elements
images	images	images	raw data
[Marr]	[Demazeau]	[Crowley]	[Neuman]

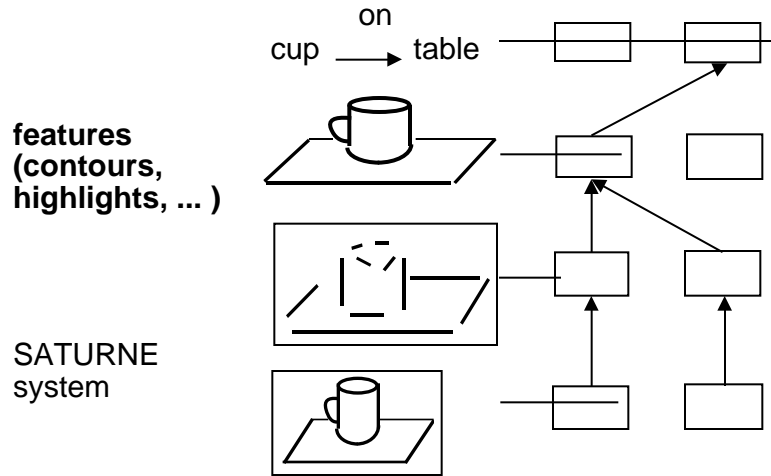
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### Decomposition by Location [Crowley 89]



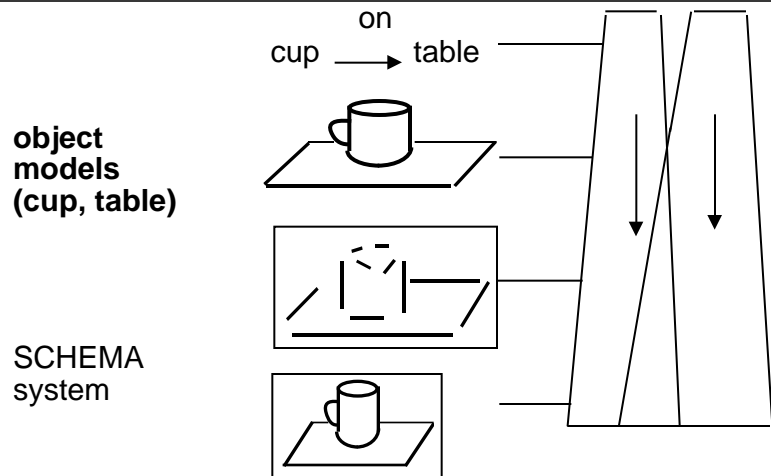
### Decomposition by Input [Demazeau 86]



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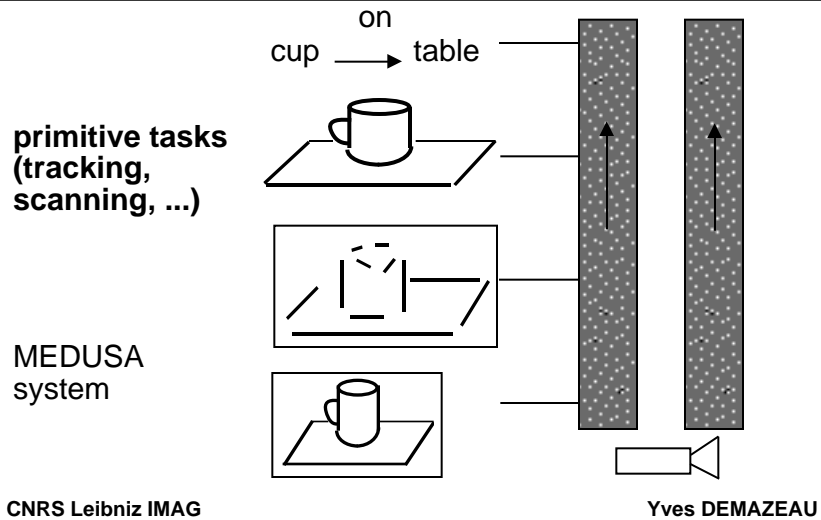
### Decomposition by Output [Draper 83]



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## Decomposition by Tasks [Aloimonos 90]



## Extrinsic Decomposition [Alvares 96]

### Characteristics

- each agent is able to solve the whole problem
- the use of many agents in parallel speeds up the problem solving
- it is a purely physical (spatial or temporal) decomposition of the work between the agents

### Examples

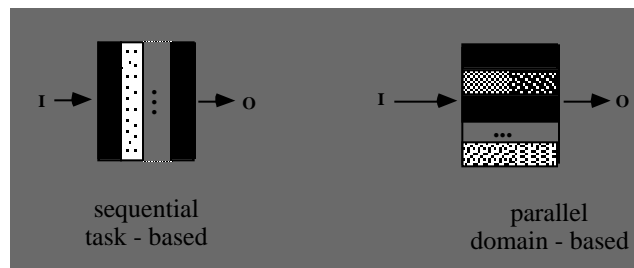
- there is an examination to be prepared by several professors. Each one will be responsible to prepare a given number of questions (spatial)
- each professor will work for a given time (temporal)

## Intrinsic Decomposition [Alvares 96]

The decomposition is based on a specialization

### Two possible ways

- to solve the problem partially for any case
- to solve the problem entirely for some cases



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## Using many criteria (1) [Alvares 96]

The criteria are not mutually exclusive, we can combine them

At every level, the decomposition criteria are exclusive

### Example: to prepare an examination subject

- Determine the number of questions and the respective value by topic (sequential)
- There will be people to prepare questions about topic t1 and people to prepare questions about topic t2 (parallel)
- In topic t1, there will be discursive and simple choice questions (parallel).
- There will be people to revise all questions (sequential)
- Each question will be revised for technical aspects and for linguistic aspects (parallel)

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## Using many criteria (2) [Alvares 96]

**The problem is decomposed into :**

- 1 determine topics 2 prepare questions 3 revise questions

**The subproblem 2 is decomposed into**

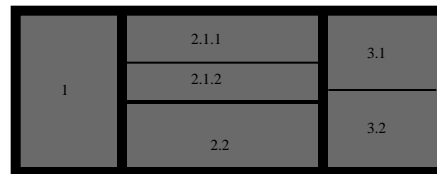
- 2.1 topic t1 2.2 topic t2.

**The subproblem 2.1 is decomposed into**

- 2.1.1 discursive questions 2.1.2 simple choice questions.

**The subproblem 3 is decomposed into**

- 3.1 technical review; 3.2 linguistic review.



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## Comparative Properties [Alvares 96]

	extrinsic	sequential task-bsd	parallel domain-bsd
<b>ag's competence and behaviour</b>	same	different	different
<b>allowance of parallelism</b>	yes	no	yes
<b>allowance of ag's simplification</b>	no	yes	yes
<b>type of decomposition</b>	quantitative	qualitative	qualitative
<b>communication between agents</b>	minimal	maximal	minimal

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## How MAS Methodology is specific ?

**= Approach + Model + Tools + Problem + Domain  
= Analysis + Design + Development + Deployment**

**It provides a new analysis and design approach**

...

## MAS Approach : Decomposing into Entities

**A new approach to analyze and design SS**

- 1. MAS are situated, and the real environment differs from the perceived environment**
- 2. The methods are mainly process-centered, but non-only task-based**
- 3. The methods involve both declarative and computational specifications**
- 4. The control is mainly decentralized, highly modular, it is distributed among entities and partly in an emergence engine**
- 5. The entry point of the design is not unique nor imposed, even usually focused on Agents first**
- 6. VOWELS decomposes the MAS into A, E, I, O**
- 7. ...**

## MODELS

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## MAGMA Models : Pluridisciplinarity

### Mathematics

- Maths : Logics, Graphs and Trees
- Maths : Geometry, Topology
- Maths : Analysis
- Maths : Algebra

### Physics

- Physics : Mechanics, Statistical Mechanics
- Physics : Automata, Control

### Other Sciences

- H&S Sciences : Social Psychology, Sociology
- H&S Sciences : Philosophy
- H&S Sciences : Economy
- N&L Sciences : Ecosystems

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## **Models : Agents and Environments**

### **Agents**

- Maths : Logics : COHIA, ASIC
- Maths : Graphs and Trees : SMAM
- Physics : Mechanics : PACO, PACO+
- Physics : Automata : SMARRPS
- Physics : Control : ASTRO
- H&S Sciences : Social Psychology

### **Environnements**

- Maths : Geometry : SMARRPS, SIGMA, AGENT
- Maths : Topology : SMAM
- Physics : Mechanics + Maths : Geometry : PACO
- H&S Sciences : Social Psychology
- Natural Sciences : Ecosystems

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## **Models : Interactions and Organisations**

### **Interactions**

- Maths : Logics + H&S Sciences : Philosophy : IL, IL2
- Maths : Graphs and Trees : IL Interaction Protocols
- Maths : Graphs and Trees : Dynamic Interaction Models
- Physics : Mechanics : PACO, SMARRPS
- H&S Sciences : Social Psych. + Philosophy : Dialogism

### **Organisations**

- Maths : Logics : PACORG
- Maths : Analysis + H&S Sciences : Economy : Markets
- Maths : Graphs and Trees : SMAM
- Physics : Mechanics : SIGMA
- H&S Sciences : Social Psychology : Social Power

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## **Models : Recursion and Emergence**

### **Recursion**

- Maths : Graphs and Trees

### **Emergence**

- Physics : Mechanics : PACO, SMARRPS
- Physics : Statistical Mechanics : PHAMUS, SMAM
- Maths : Algebra + H&S Sc. : Sociology : ((A + I) + O) + E)
- H&S Sciences : Social Psychology : Social Power
- N&L Sciences + H&S Sciences

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## **How MAS Methodology is specific ?**

**= Approach + Model + Tools + Problem + Domain**  
**= Analysis + Design + Development + Deployment**

**It provides a new analysis and design approach**

**It is supported by existing formalisms,**

...

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## **MAS Models : Modelling these Entities**

### **New models supported by existing formalisms**

- 1. At higher abstraction level than other existing methods, closer to natural human way of thinking and reasoning about systems, not only devoted to computer scientists**
- 2. It does not supply any new formalism currently, but entities are formalized using existing formalisms like traditional logics, Petri nets, algebraic languages, design patterns,...**
- 3. VOWELS As range from reactive to cognitive**
- 4. VOWELS Es range from spatial to topological**
- 5. VOWELS Is range from forces to speech acts**
- 6. VOWELS Os range from groups to markets**
- 7. ...**

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## **DEVELOPMENT**

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## Evolution of Programming Paradigms

### 1950's

- Machine and assembly language

### 1960's

- Procedural programming

### 1970's

- Structured programming

### 1980's

- Object-Based programming, Declarative programming

### 1990's

- Frameworks, design patterns, scenarios, and protocols

### 2000's

- Agents... Multi-Agent Systems...

...

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## Features of Languages and Paradigms

Concept	Proc. L.	Object L.	Agent L.
<b>abstraction</b>	type	class	society
<b>building block</b>	data	object	agent
<b>computational model</b>	procedure call	method message	perceive reason / act
<b>design paradigm architecture</b>	tree of procedures	interaction patterns	cooperative interaction
<b>modes of behavior terminology</b>	functional decompos. coding implement	inheritance polymorph. designing and using engineer	managers assistants,peers enabling and enacting activate

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## **Agent Oriented Programming [Shoham 93]**

### **A complete AOP system will include three primary components**

- a restricted formal language with clear syntax and semantics for describing mental state: the mental state will be defined uniquely by several modalities, such as belief and commitment
- an interpreted programming language in which to define and program agents, with primitive commands such as REQUEST and INFORM: the semantics of the language will be required to be faithful to the semantics of the mental state
- an "agentifier", converting neutral devices into programmable agents.

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## **AOP vs. OOP : introduction**

- The use of mental states is to design the computational system
- From an engineering point of view, AOP can be viewed as a specialization of OOP, in the original sense of Hewitt's Actors model
- OOP proposes viewing a computational system as made up of modules that are able to communicate with one another and that have individual ways of handling incoming messages
- AOP specializes the framework by fixing the state (mental state) of the modules (agents) to consist of components such as beliefs (about the world, about themselves, about one another), capabilities, and decisions, each of which enjoys a precisely defined syntax.

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## Components of mental state

### Components of mental state

- the future is determined by two factors : past history and current actions of agents.

### The actions of an agent are determined by its decisions, or choices

### Decisions are logically constrained, though not determined, by the agent's beliefs

- These beliefs refer to the state of the world, to the mental state of other agents, and to the capabilities of this and other agents

### Basics : beliefs, capabilities, obligations (decision is simply an obligation to oneself)

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## A language for belief, obligation, and capabilities

time / action    holding(robot,cup)<sup>t</sup>

belief             $B_a^t \varphi$              $\varphi$  a (recursive) sentence

obligation         $OBL_{a,b}^t \varphi$

decision            $\equiv_{\text{def}} OBL_{a,a}^t \varphi$

capability          $CAN_a^t \varphi$   
 $ABLE_a \varphi =_{\text{def}} CAN^{\text{time}(\varphi)}_a \varphi$

time( $\varphi$ ) the outermost time occurring on

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### Properties of the various components

<b>internal consistency</b>	$\forall a, t \{ \varphi : B_a^t \varphi \}$ is consistent $\forall a, t \{ \varphi : OBL_{a,b}^t \varphi \}$ is consistent
<b>good faith</b>	$\forall t, a, b, \varphi \ OBL_{a,b}^t \varphi \supset B_a^t ((ABLE_a \varphi) \wedge \varphi)$
<b>introspection</b>	$\forall t, a, b, \varphi \ OBL_{a,b}^t \varphi \equiv B_a^t OBL_{a,b}^t \varphi$ $\forall t, a, b, \varphi \neg OBL_{a,b}^t \varphi \equiv B_a^t \neg OBL_{a,b}^t \varphi$
<b>persistence</b>	so are mental state, obligations
<b>capability</b>	capabilities do not fluctuate widely

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### Agent0 : basic loop

#### The role of agent programs is to control the evolution of an agent's mental state

- actions occur as a side-effect of the agent's being committed to an action whose time has come

#### Each agent iterates the following two steps at regular intervals

- read current messages, and update your mental state, including your beliefs and commitments (the agent program is crucial for this update)
- execute the commitments for the current time, possibly resulting in further belief change (this phase is independent of the agent's program)

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## **Interaction Oriented Programming [Huhns 96]**

### **Motivations**

- errors will always be in complex systems;
- Error-free code can be a disadvantage;
- Where systems interact with the real world, there is a power that can be exploited

### **Example : children forming a circle**

- conventional approach: create a C++ class for each type of object, write a control program that uses trigonometry to compute the location of each object
- interaction-oriented approach: children approach is robust due to local intelligence and autonomy, write the program based on objects having attitudes, goals, agent models

**IOP : Active modules, declarative specification, modules that volunteer, modules holdbelief about the world, especially about themselves and others**

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## **Organisation Oriented Programming [Lemaitre 98]**

**Designing, Maintaining, Using MAS utilize different integrative frameworks that include features to deal with agents, interactions, environments, ... MAS programming itself follows history of programming.**

**The most well-known effort towards MAOP is AOP [Shoham 93] ... IOP [Huhns 97] is an alternative...**

**OOP is another one [Lemaitre 98] ... EOP does not actually exist as a trend but looks like Artificial Life.**

**These approach respectively focus on Agents, on Interactions, on Organisations, on Environments, as being the respective basic bricks at the disposal of the designer / MAS / user...**

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**(((A + I) + O) + E) O.Programming [Demazeau 96]**

**The Population structure is the set of agents, the set of possible behaviors of the agents, and the set of all interaction processes between agents**

**Pop = (Ag, Bh, Ip; bc, ic)**

**Ag** : set of agents

**Bh** : set of behaviors agents are able to perform

**Ip** : set of interaction processes

**bc** : Ag  $\rightarrow$  P(Bh), behavioral capability,  
bc(a), set of behavior a is able to perform

**ic** : Ag x Ag  $\rightarrow$  P(Ip), interaction capability,  
ic(a1,a2), set of interaction processes  
agents a1 and a2 may perform together

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**(((A + I) + O) + E) OP : Organisations**

**The Organization structure is composed of organizational roles and organizational links**

**Org = (Ro; Li)**

**Ro is defined in a relational way**

- e.g. Ro Lp x Gp : global processes (Gp) and local processes (Lp), the role is the part of agent's behavior that is integrated in the global process.
- e.g. Ro Fo x Lv : foci of interest (Fo), representation levels (Lv), the role is the agent's behavior for a given focus at a given level.

**Li  $\subseteq$  Ro x Ro**

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**(((A + I) + O) + E) OP : Pop  $\mathfrak{R}$  Org = imp**

**The suitable relation between the organization and the population of a system is called the system's organization implementation**

**It is any relation  $\text{imp} = \text{Pop} \mathfrak{R} \text{Org}$ , on  $(\text{Ro} \times \text{Ag}) \cup (\text{Li} \times \text{Ip})$ ,  $\text{Pop} = (\text{Ag}, \text{Bh}, \text{Ip}; \text{bc}, \text{ic})$ ,  $\text{Org} = (\text{Ro}; \text{Li})$ .**

- if  $(r, a) \in \text{imp}$ ,  $r$  is said to be implemented by  $a$
- if  $(l, p) \in \text{imp}$ ,  $l$  is said to be implemented by  $p$

**imp is said "proper" iff  $\mathfrak{R}$  is an homomorphism.**

- $r \in \text{Ro}$ ,  $a \in \text{Ag} / (r, a) \in \text{imp}$ , and  $r$  is properly implemented by some behavior  $b \in \text{bc}(a)$
- $l = (l1, l2) \in \text{Li}$ ,  $ip \in \text{Ip} / \{ (l, ip) \in \text{imp} \mid (a1, a2) \in \text{Ag} \times \text{Ag} / ip \mid \text{ic}(a1, a2), (r1, a1) \in \text{imp}, (r2, a2) \in \text{imp}, \text{ and } r1, r2 \text{ are properly implemented by the behaviors of } a1 \text{ and } a2, \text{ respectively} \}$

**(((A + I) + O) + E) OP : PopOrgs**

**The Interior ( = Population + Organisation ) of a time-invariant multi-agent system is captured by a population-organization structure  $\text{PopOrg} = (\text{Pop}, \text{Org}; \text{imp})$ , where**

- $\text{Pop} = (\text{Ag}, \text{Bh}, \text{Ip}; \text{bc}, \text{ic})$  is a population structure
- $\text{Org} = (\text{Ro}; \text{Li})$  is an organization structure
- $\text{imp} = (\text{Ro} \times \text{Ag}) \cup (\text{Li} \times \text{Ip})$  is an organization implementation relation as defined previously

## **Multi-Agent Oriented Programming**

### **Not Object-Oriented Programming**

- S = Objects + Message passing

### **Not Logic nor Expert Systems Programming**

- S = Knowledge + Inference Mechanism

### **Not Ontology-Oriented Programming**

- S = Knowledge + Problem Solving Methods

### **But Agent-Oriented Programming**

- S = BDI Agents + KQML (Interactions)

### **But (((A + I) + O) + E)-Oriented Programming**

- S = ((A + I) + O) + E)

### **But VOWELS Programming**

- S = [A\*; E\*; I\*; O\*] + (Recursion & Emergence) Mechanism

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## **How MAS Methodology is specific ?**

**= Approach + Model + Tools + Problem + Domain  
= Analysis + Design + Development + Deployment**

**It provides a new analysis and design approach**

**It is supported by existing formalisms,**

**It integrates existing programming paradigms,**

...

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## **MAS Tools : Developing these Entities**

### **New tools integrating existing paradigms**

- 1. MAS is not (yet?) an implementation model and MAS oriented tools are usually not specific**
- 2. Agents themselves just begin to have their own languages**
- 3. MAS Development relies on existing languages and programming paradigms**
- 4. The trend of the work is towards Multi-Agent Oriented Programming, meaning programming MAS with MAS tools**
- 5. The closest related tools for VOWELS seems be frameworks but are still under investigation from the computational point of view**
- 6. ...**

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## **DEPLOYMENT**

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## Object-Based (Concurrent) Languages

### Actors-like Languages

- Massive Parallelism
- Every interaction is made by passing of asynchronous buffered messages
- Use of the local continuity
- Object-oriented design
- Full distributed control

### Actors [Hewitt]

- An actor is composed of acquaintances, scripts, ...
- A message is an actor containing method, continuation, and complaint actors
- A method is a set of actions : create a new actor, send a message, modify actor's behaviour

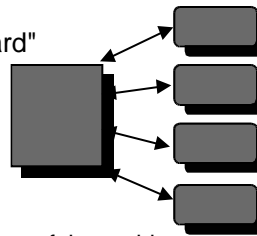
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## (Distributed) Blackboard Systems

### BB-Like frameworks

- Interactions through the "blackboard"
- Opportunistic activation of the knowledge sources
- Initially Centralized Control



### DBB

- Blackboard
  - ✓ A global database representing state of the problem
  - ✓ Hierarchically organised into levels of granularity
- Knowledge Sources
  - ✓ Produce changes (hypotheses) onto given levels of BB
  - ✓ Contain particular subset of domain knowledge
- Centralized Control
  - ✓ Evaluates the status of the problem
  - ✓ Controls the knowledge sources

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## **Integrative Environments**

### **Language for constructing agents**

- Different agent architectures
- Language for knowledge representation
- Mechanisms for reasoning, deciding, controlling

### **Representing and dealing with the environment**

- Representation of the environment and its evolution
- Implementing the perception of the environment
- Implementing the actions of the agents in the environment

### **Representing and dealing with other agents**

- Primitives, protocols, message processing
- Implementing communication between agents

### **Development Interface**

- Visualisation, trace, inputs-outputs

### **Application Interface**

### **Interface with Target (Distributed or not) System**

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## **PACT [Cutkosky]**

### **Palo Alto Collaborative Testbed**

#### **Computer-Aided Concurrent Engineering**

- Stanford, Lockheed, Hewlett-Packard, Enterprise Integration Technologies
- Have integrated four pre-existing CE systems into common distributed framework supporting aspects of small robot

#### **Uses quasi-standards**

- Knowledge Interchange Format (KIF) [DARPA-92]
- Knowledge Query & Manipulation Language (KQML) [Finin-92]
- Product Data Exchange Specification (PDES)

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## **MASK [Occello]**

**Applications** ( .. MAGIC, GEOMED, SMAALA, SIGMA, Le Salon, SPANS.. )  
(Boissier-94)(Ferrand-95)(Baeijs-95)(Van Aeken 96)

### **Agents**

(Boissier-93)  
(Ferrand-95)  
(Sichman-95)  
(Occello-96)

### **Environments**

(Demazeau-90)  
(Ferrand-94)  
(Baeijs-95)

### **Interactions**

(Koning-94)  
(Demazeau-95)  
(Ferrand-96)  
(Pesty-96)

### **Organisations**

(Baeijs-95)  
(Demazeau-96)  
(Kozlak-96)  
(Van Aeken-96)

**XENOOPS** (Joosens-94)

**JAVA** (Sun™-95)

Network of Sun-Like Workstations

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## **How MAS Methodology is specific ?**

**= Approach + Model + Tools + Problem + Domain**  
**= Analysis + Design + Development + Deployment**

**It provides a new analysis and design approach**

**It is supported by existing formalisms,**

**It integrates existing programming paradigms,**

**It is striving towards industrial quality,**

...

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## Todays offer

### Academics

- Firefly (MIT before Microsoft) (no more accesible)
- MadKit (LIRMM Montpellier - Ferber's group)
- Simula (II Porto Alegre - Alvares's group)
- dMARS (-> Jack, by Agent Oriented Software)
- *From 2000* : Volcano...

### Industrials

- Voyager (ObjectSpace) - freeware (linked with OMG)
- JINI (Sun) - freeware
- Aglets (IBM) - freeware
- Javabeans (Sun) - freeware (based on components)
- Agentbuilder (Reticular) - freeware + product (AOP based)
- ZEUS (BT) - freeware product (FIPA compliant)
- *From 2000* : JADE, Jack...

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## Qualification criteria

### Four *qualities* for each stages:

- Completeness: quantity & quality
- Applicability: scope, restrictions
- Complexity: competence required, workload
- Reusability: reuse of previous work

### 16 criteria + availability & support

	Analysis	Design	Development	Deployment
Completeness				
Applicability				
Complexity				
Reusability				

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## Selected platforms

### Platforms requirements :

- based on a strong academic model
- high quality software, well maintained
- cover as many aspects as possible of MAS
- cover the four methodological stages

### AgentBuilder, Jack, Madkit, Zeus

- As of first semester 2000

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## Jack™

Developed by Agent Oriented Software Pty.

Including the dMARS BDI model

Great versatility

Focus on the development stage

	Analysis	Design	Development	Deployment
Completeness	none	ident. of classes	extended Java	manual
Applicability	n / a	Jack BDI A	Any MAS	n / a
Complexity	n / a	Jack BDI A	Java & Logic P.	n / a
Reusability	n / a	difficult	classes	n / a

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## MadKit

Developed by O. Gutknecht & J. Ferber, LIRMM

Based on the AALAADIN organisational model  
Graphical multi-agent runtime engine

Good versatility

Light methodology, no BDI

	Analysis	Design	Development	Deployment
Completeness	none	Aalaadin	Pure Java	G-Box
Applicability	n / a	broad range	simple A	small large MAS
Complexity	n / a	intuitive	few code base	GUI
Reusability	n / a	design patterns	classes	dynamic reconf.

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## AgentBuilder®

Developed by Reticular Systems Inc.

Grounded on Agent0/Placa BDI architecture

Almost all stages covered

Complete graphical tools

Limited to a single agent model

	Analysis	Design	Development	Deployment
Completeness	ontology	A definition	behavioural rules	RT A engine
Applicability	universal	cognitive A	AgentBuild. BDI	small societies
Complexity	OO GUI	MAS design GUI	Logic P. GUI	GUI
Reusability	ontology	protocols	A	none

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## Zeus

Developed by British Telecom

All stages covered, from analysis to deployment  
Methodological and Software tools  
Limited to a single agent model

	Analysis	Design	Development	Deployment
Completeness	role modelling	finding solutions	5 activities	tools docs
Applicability	role o. MAS	task o. A	Zeus A model	debug visualis.
Complexity	UML	design skills	GUI tools	GUI
Reusability	role models	reusable formal.	partial	A reconf.

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## Pitfalls of current MAS offers

### Completeness

- Much on development... nothing about analysis/design
- Much focus on approach... but poor technical aspects
- Nothing about deployment
- Every stage must be developed in the platform !

### Applicability

- An agent platform...but not a multi-agent platform
- A generalisation of a specific multi-agent system  
...multi-domain, but single-problem platform
- Fixed models, and no way to escape
- The platform must be as versatile as possible !

### Complexity

- The documentation is sparse
- You have to code a lot
- The user interface is unfriendly
- Understanding, (re)using the platform must be facilitated !

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## **Volcano**

**Developed by PM. Ricordel & Y. Demazeau, LEIBNIZ**

### **A multi-agent platform to fulfil all these criteria**

- Based on the AEIO MAS decomposition [Demazeau]
- Full analysis-to-deployment chain
  - ✓ Problem/domain decomposition
  - ✓ AEIO modelling
  - ✓ Open library of models (simplicity, versatility, reusability)
  - ✓ Intelligent deployment tools

### **But**

- Still under development...
- Looking for partners
- To be fully evaluated...

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## **METHODOLOGY**

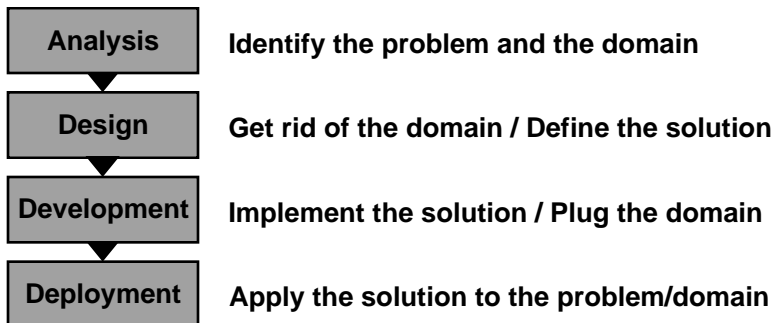
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## MAS Methodology

### Methodology

= Approach + Model + Tools + Problem + Domain  
= Analysis + Design + Development + Deployment



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## MAS methods vs. Systemic methods

### Systemic Methods meaning...

- Information Systems

### Characteristics of the Systemic Methodology

- data-centered
- centralized
- almost not modular

### Characteristics of the MAS Methodology

- mainly process-centered
- decentralized
- highly modular

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## MAS methods vs. Formal methods

### Formal (Specification) Methods meaning...

- Logics, Algebraic languages like Z, Automatas, Petri Nets, ...

### Characteristics of the FS Methodology

- mainly used for validation
- include automatic generation

### Characteristics of the MAS Methodology

- very low supported by a dedicated formal framework, but...
- ... possible use of existing formalisms to specify MAS components
  - ✓ logics-based approach [Fischer 94], [Huntbach 95], ...
  - ✓ Z, algebraic language approach [Luck 95], ...
  - ✓ Petri Nets approach [Elfallah 96], ...

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## MAS methods vs. Knowledge methods

### Knowledge (Representation) Methods meaning...

- KADS, CML, KSM [Molina 95]...

### Characteristics of the KR Methodology

- mainly declarative specifications
- control lays in the system inference engine

### Characteristics of the MAS Methodology

- both declarative and computational specifications [Glaser 96], ...
- control lays in processing units and an emergence engine
  - ✓ (agent) control lays in the processing units [Occello 97], ...
  - ✓ (MAS) control lays in the system emergence engine, this engine involves the processing units with a recursion principle, whichever they are agents, environments, interactions, organisations [Demazeau 95], ...

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## **MAS methods vs. Functional methods**

### **Functional Methods meaning...**

- SART, ...

### **Characteristics of the Functional Methodology**

- task-based
- hierarchical
- decision as automata
- global context

### **Characteristics of the MAS Methodology**

- non-only task-based [Alvares 97], ...
- hierarchical and possibly recursive [Occello 97], ...
- reactive and cognitive decision [Brazier 95], [Jonker 98], ...
- global and local contexts [Drogoul 98], ...

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## **MAS methods vs. Object methods (start)**

### **Object Methods meaning...**

- OO analysis and design, modelling, implementation

### **Characteristics of the Object Methodology**

- continuity Approach / Modelling / Implementation
- ...

### **Characteristics of the MAS Methodology**

- no full continuity Approach / Modelling / Implementation
  - ✓ MAS is not (yet?) an implementation model
  - ✓ Agents just begin to have their own languages [Shoham 93], [Thomas 95], ... but the programming is not always based on Agents [Demazeau 97]
  - ✓ MAS design is based on existing languages and programming paradigms [Poggi 94], ...
  - ✓ towards multi-agent oriented programming [Demazeau 97], ...
- ...

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## **MAS methods vs. Object methods (cont'd)**

### **Characteristics of the Object Methodology**

- object classes
- inheritance mechanism
- no organisation nor group primitives
- objects are built first, and then their dynamics
- ...

### **Characteristics of the MAS Methodology**

- Agents, Environments, Interactions, Organizations [Demazeau 95], ...
- component groups, recursive mechanism [Fisher 94], [Kinny 96], [Occello 97], ...
- organisation and group primitives [Occello 97], ...
- entry point of the design is not unique nor imposed [Demazeau 97], ... even it often corresponds to agents
- ...

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## **MAS methods vs. Object methods (end)**

### **Characteristics of the Object Methodology**

- environnement of an object does not exist, even if the environment of an object system does
- fixed Data Interaction Model
- global control, RPC mechanism,

### **Characteristics of the MAS Methodology**

- MAS are situated, the real environment differs from the perceived environment [Moulin 95], [Kendall 95], ...
- free Data interaction Model [Demazeau 95], ...
- global (protocols) [Demazeau 95], [Koning 98], ... and local control (agent's decision) [Shoham 93], [Kendall 95], ...

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## **MAS methods vs. Components methods (start)**

### **Components Methods meaning...**

- Components meaning JavaBeans, MS-COM, ...

### **Characteristics of the Components Methodology**

- continuity Approach / Modelling / Implementation
- fixed Data Interaction Model between components
- no organisation nor group primitives
- components are built first, and then their dynamics

### **Characteristics of the MAS Methodology**

- no full continuity Approach / Modelling / Implementation
- free Data interaction Model [Demazeau 95], ...
- organisation and group primitives [Occello 97], ...
- entry point of the design is not unique nor imposed [Demazeau 97], ... even it often corresponds to agents

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## **MAS methods vs. Components methods (end)**

### **Some common features between the methods**

- introspection, persistence, mobility of basic entities
- event-driven communication between entities
- entities design and integration into applications

### **Characteristics of the Components Methodology**

- customisation of entities at design time only
- existing de facto standards towards interoperability
- application independent reusable interoperable entities

### **Characteristics of the MAS Methodology**

- possible dynamic allocation of roles during run time
- efforts to standardisation through the FIPA foundation
- still frequently application dependent entities

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### **How MAS Methodology is different ? (start)**

**An enriched process-centered, decentralized, highly modular information system methodology**

**A currently poorly formalized formal specification methodology, reusing existing formalisms**

**An enriched knowledge representation methodology with computational specifications, a decentralized control and an emergence engine**

**An enriched functional methodology, not-only task-based, with possible recursion, cognitive decision, and local contexts**

...

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### **How MAS Methodology is different ? (end)**

**An enriched but incomplete object methodology**

- with extended classes (A, E, I, O), groups, organizations, recursive mechanism, and where the design is not always based on agents,
- with situated agents, free interactions, local control,
- where the programming is not always based on agents, but where no full continuity Analysis / Design / Implementation is not yet achieved

**An close component methodology, more flexible but still to be standardized**

**An enriched UML methodology which is not restricted to the design of systems**

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## **Existing MAS methods and current work**

### **Australia**

- Kendall (Melbourne), Kinny (Melbourne), ...

### **France**

- Barthes (Compiègne), Cazalens (Nantes), Demazeau (Grenoble), Ferber (Montpellier), Glize (Toulouse), ...

### **Netherlands**

- Treur (Amsterdam), ...

### **Spain**

- Garcia (UPM), ...

### **UK**

- Jennings (Southampton), Wooldridge (Liverpool), ...

### **USA**

- Shoham (Stanford), ...

...

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## **CASSIOPEE : General Issues**

### **From the Analysis of natural organisations to the Design of artificial organisations**

### **Based on several applications and experiments**

### **Three Abstraction Levels**

- individual agents, interactions, organizations

### **Agents is defined as a set of Roles**

- individual roles, interactional roles, organizational roles

### **Lacks of Models and Tools**

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## CASSIOPEE : Abstraction Levels

### Agents

- Which architecture to choose to implement the agents ?
- Which scope of knowledge and how to best use it ?
- Which competences and how are they distributed ?

### Interactions

- How do agents communicate ?
- Which content ?
- Can agents influence / alterate other's behaviour ?

### Organisations

- How do the agents cooperate ?
- Is there a global goal, how to build a plan to reach it ?
- Which structure to organize, which evolution of the structure ?

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## CASSIOPEE : Composing Roles

### Domain & Problem Dependent Typology of Roles Individual Roles

Getting abstracted from the Domain  
by Resource / Functional Dependence  
(conflicts, permits, facilitates, needs, ...)

### Problem based Typology of Relational Roles Interactional roles (influencing, influenced)

Getting abstracted from the Problem  
by Identification of Potential Groups  
(SIGs, ...)

### Typology of Organizational Roles

Organizational roles (initiator, participant)

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## **DESIRE : General issues**

### **Design and Specification**

- Complex reasoning systems in general
- Proposes a powerful design tool
- A design approach more than an analysis approach

### **A Formal Framework**

- Formal specifications to automatically generate a prototype

### **Interacting Components based**

- Input/output components

### **Reflective**

- reasoning
- architecture

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## **DESIRE : A Specification Framework**

### **Components Decomposition**

- Components Hierarchy
- Primitive and composed components

### **Information Exchange between Components**

- Information links for information flows (channels)
- different levels of dynamic interaction models

### **Sequencing of tasks**

- a local control process in each component
  - ✓ rules set (facts)
  - ✓ required data (required interactions)

### **Hierarchical knowledge structures**

- adapted to components granularity

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## DESIRE : Modeling Agents

### Models

- Agents as composed components
- Modeling of specific types of Information Exchange
  - ✓ more communication than interaction
  - ✓ MAS interaction = components interaction
  - ✓ interaction is embedded in components

### Approach

- A task based approach (functional)
  - ✓ no explicit AEIO models

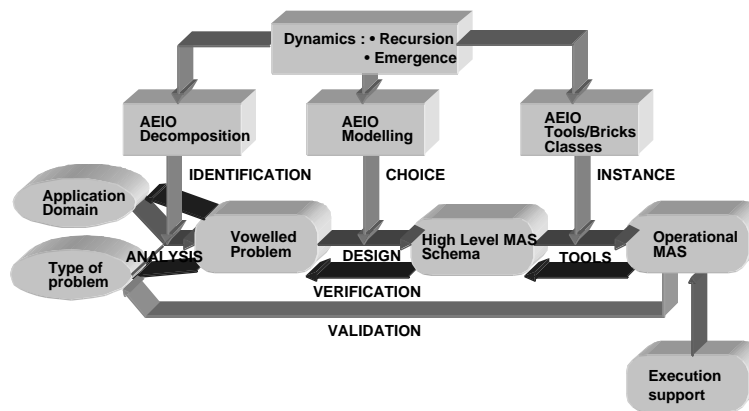
### Design

- An agent centered approach
  - ✓ no external expression of interaction
  - ✓ no external expression of organisation

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## VOWELS : Methodology



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## VOWELS : Analysis

$((A + I) + O) + E$	<b>Social Science</b>
$((A + E) + I) + O$	<b>Robotics Science</b>
$((E + A) + I) + O$	<b>Life Science</b>
$((I + O) + A) + E$	<b>Military Science</b>
$((O + I) + E) + A$	<b>Economic Science</b>

...

**Historical ? Biased ? Grounded ?**

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## VOWELS : Design

### **Agents**

- internal architectures of the processing entities

### **Environment**

- domain-dependent elements for structuring external interactions between entities

### **Interactions**

- elements for structuring internal interactions between agents

### **Organizations**

- elements for structuring sets of agents within the multi-agent system

**These definitions are agent-centered but alternatives exist, firstly based on environments, on interactions, or on organisations.**

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## VOWELS : Development

**The Declarative Principle**  
**MAS = A + E + I + O**

**The Functional Principle**  
**Function(MAS) =  $\sum$  Function(A)**  
**+ Emergence Function**

**The Recursive Principle**  
**A = basic A | MAS**

**These principles are agent-centered but alternatives exist : any recursion dealing with A, E, I, O or any combination of the four basic elements**

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## VOWELS : Deployment

### **MASK - Platform**

- MASK Design, Agent (API, ASTRO, SIGMA)
- Interaction (API, IL, Protocols), Organisation (RESO)
- Integration and Illustrations : Conveyors, Factorial, Appointment service

### **VOLCANO - Platform**

- VOLCANO Design
- A E I O components and interfaces
- Integration
- Illustrations : Robocup, Appointment service, SMAMS

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## **VOWELS : Usage**

**MAOP subsumes AOP, IOP, OOP-like OP...**

**We defend an instance of MAOP, the VOWELS framework in which :**

- 1/ to express the problem to solve independently of the domain
- 2/ to "vowellify" the problem in terms of A E I O, ...
- 3/ to choose understood frames of A, E, I, O, dynamics, and recursion
- 4/ to leave VOWELS "emergence engine" complete the missing bricks by itself and build the appropriate MAS...
- 5/ ... to be deployed as self on a distributed settling...
- 6/ ... to be settled and used interactively

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## **APPLICATIONS**

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## SIGMA (academic project)

A reactive multi-agent approach to cartographic generalization LIFIA-INPG (F), IGN (F)

Interaction and organisation modelling to study their reciprocal interdependencies

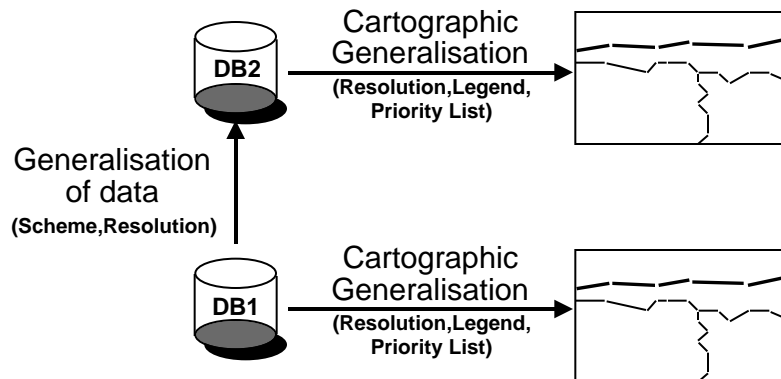
### Approach

- following the PACO approach ( multiple types + organizational knowledge)
- reaching the relative importance of data types according to a desired global goal
- operators to transform the representations of the data and the possible changes of scale
- interactive validation
- Implementation on C/C++ on Sun WS - LAN/XENOOPS

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## SIGMA : Types of Generalisation



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## **SIGMA : Principles**

### **Partial automatizing of cartographic generalization**

- Creation of a readable and useful cartographic map from a geographical database given the aim of the map (pre-order) and using a non-holistic approach
- Modelling agents, interactions and organizational structures, and studying the convergence effects

### **Extension of the PACO paradigm**

- Geographical objects are represented by a collection of "geographical entities" which "may" become agents
- Introduction of organizational knowledge to study their impact on a local level (behaviour of the agents) as well as on a global level (convergence of the system)

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## **SIGMA : Model : E and A**

### **Environment**

- Geographical entities placed on a 2D grid, initially corresponding to the raw data (World of Reference)
- Active work on a copy (Active World) of the initial world to offer the opportunity to later geographical verification mechanisms

### **Agents**

- A geographical entity becomes an agent as soon as its position in the organization (its mass) is important enough with respect to the aim of the map
- Each agent possesses several self-controlled scopes:
  - ✓ Perception (local environment)
  - ✓ Communication (class, object, proximity, groups)
  - ✓ Action (class, object, proximity, groups)

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## SIGMA : Model : I and O

### Interactions

- Between artificial agents (or objective groups)
  - ✓ Repulsion Force
  - ✓ Proportional Following (against local deformation of objects)
  - ✓ Unconditional Following (agents "sticking" together)
  - ✓ Change of symbolization
- Between the user and the agents (or subjective groups)
  - ✓ Change of symbolization
  - ✓ Formation or breaking of topological structures
  - ✓ Displacement of agents

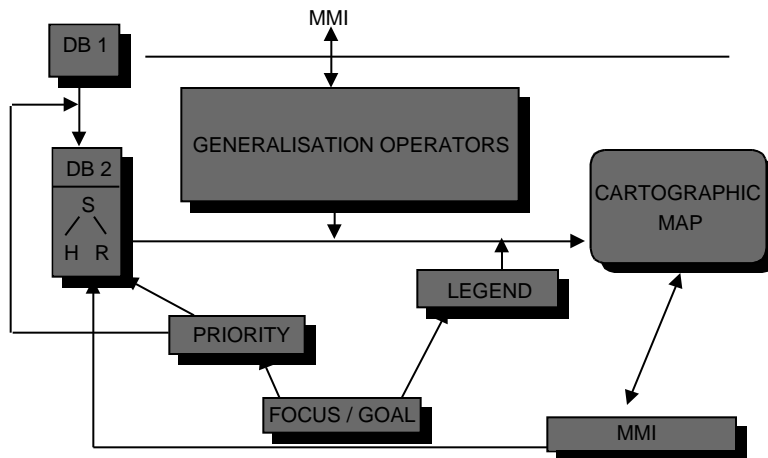
### Organizations

- Pre-orders, figuring "power"- relationship between geographical classes
- Groups, consisting of agents sharing the same local environment to realize a common task

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## SIGMA : The Architecture of the System



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## SIGMA : Implementation and Results

### Implementation

- Full implementation in C++ under Unix with acceptable results

### Results

- "Les Matelles": • 300 objects -> 1800 geo. entities  
acceptable results in quality and computation
- "Neighbourhood of Les Matelles": • 2000 objects -> 15000  
geo. entities • acceptable results in quality

### Perspectives

- Full explicitation of the organizational issues in the system
- Distribution/Parallellization of the system using XENOOPS
- Followup within the CEC-IT-LTR AGENT project

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## SIGMA : Les Matelles : initial map



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**SIGMA : Les Matelles : final map**



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**SIGMA : Les Matelles : Details**

**Before**



**After**

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**SIGMA : Les Matelles Surroundings : initial**



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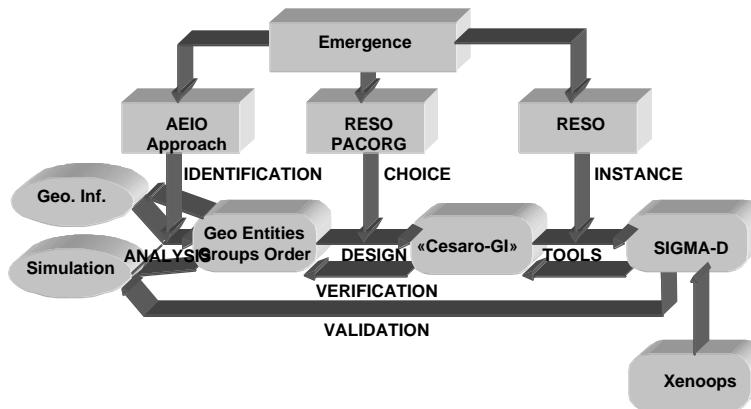
**SIGMA: Les Matelles Surroundings : final**



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## VOWELS : SIGMA-D



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## AGENT (EU project - IT-LTR 24939)

**Automatic Generalisation New Technology IGN (F),**  
LaserScan Ltd. (UK), LEIBNIZ-INPG (F), U. Zürich  
(CH), U. Edinburgh (UK)

**Automated generalisation to provide maps from  
cartographic databases**

### Approach

- COHIA agent architecture, micro agents (independent generalisation), meso agents (contextual generalisation), macro agents : an heterogeneous system
- Simple IL interaction mechanisms but sophisticated generalisation operators
- Recursive organisations between agents
- Full implementation on GOTHIC/LAMPS2 - Sun WS and PC - LAN & WWW - Commercialized

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## AGENT : Results



AVANT

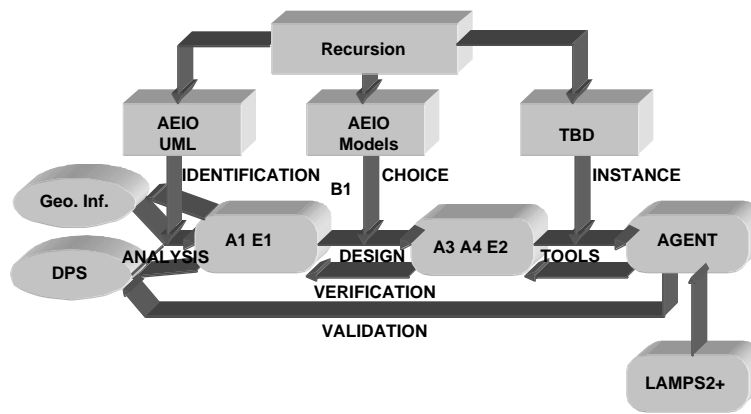
APRES



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## VOWELS : AGENT



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## TOOLS

### **MASK - Platform**

- MASK Design, Agent (API, ASTRO, SIGMA)
- Interaction (API, IL, Protocols), Organisation (RESO)
- Integration and Illustrations : Conveyors, Factorial, Appointment service

### **MAOP - Programming**

- Parallelisation
- (((A + I) + O) + E) Programming
- VOWELS

### **VOLCANO - Platform**

- VOLCANO Design
- A E I O components and interfaces
- Integration
- Illustrations : Robocup, Appointment service, SMAMS

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## VOWELS Past Applications

**Learning to Walk** : Freddy Walker (aca. VUB)

**Image Feature Tracking** : PACOVISION (ind. EAP)

**Scene Understanding** : MAGIC (aca. PRC-CHM)

**Understanding Written French** : TALISMAN (EU IT)

**Und. Written Portuguese** : NALAMAS (aca. CNPq)

**Linear Planning** : SMAALA & SANPA (ind. CERREP)

**Negotiation** : Le Salon & GEOMED (EU Telematics)

**Cartographic Generalisation** : SIGMA (ind. IGN)

**Socializing the WWW** : Friends (ind. FT)

**Resource Management** : Fishbanks (aca. CIRAD)

**Cartographic Generalisation** : AGENT (EU ESPRIT)

**Autonomous Robots** : Robocup (aca. project)

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### **Which applications are better handled by MAS ?**

**MAS methods cater for distributed intelligence applications : Network based, Human involved, Physically distributed, Decentralized controlled, ...**

**It suits when only local computational models are available whilst global ones are unknown**

- Telecommunications, Internet Applications, Vision, NLP, ...

**It is adequate for application domains and kinds of problem as soon as non-provability is acceptable**

- Vision, Robotics, NLP, GIS, Societies Simulation, ...

**It suits when the human is involved in the life cycle of a distributed system**

- Internet Applications, Groupware, CSCW, GIS, ...

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### **How MAS Methodology is specific ?**

**= Approach + Model + Tools + Problem + Domain  
= Analysis + Design + Development + Deployment**

**It provides a new analysis and design approach**

**It is supported by existing formalisms,**

**It integrates existing programming paradigms,**

**It is striving towards industrial quality,**

**It caters for distributed intelligence applications,**

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## CONCLUSION

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## Issues driving to the use of MAS

### Availability of supporting technologies

- network Capacity 78%
- processor performance 48%
- software Language and Tool Power 11%

### Inherent distribution

- physical
- organizational

### System openness

- changing system structure
- uncertain environment

### Competitive collaboration

- multiple knowledge domains
- multiple solution methods

### Natural or social systems modelling

...

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## Issues refraining to the use of MAS

### **Social acceptability of MAS applications**

- degree of delegation (trust by users)
- degree of autonomy (responsability of owners)

### **Important properties cannot be guaranteed**

- deadlock avoidance
- convergent negotiation

### **Impossibility to prove system behaviour**

- prediction of system behaviour
- validation of system behaviour

### **Transfer from research to industry**

- first to market has greater impact than best technology
- theoretical / formal MAS research have little impact

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## How MAS Methodology is specific ?

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**= Analysis + Design + Development + Deployment**

**It provides a new analysis and design approach**

**It is supported by existing formalisms,**

**It integrates existing programming paradigms,**

**It is striving towards industrial quality,**

**It caters for distributed intelligence applications,**

**It will always imply difficulties in provability.**

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## **MAS Principles**

### **MAS generates revenue**

- New applications viable
- Reduces risk of building the applications
- Encourages reusability

### **Widespread adoption of MAS requires**

- Methodology
- Industrial strength toolkits
- Standards

### **Deployment of lead applications requires**

- Use of simple, well understood techniques
- Focus on application value NOT technology
- Industrial partnership

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## **MAS Research issues**

**The problem lays in the relations between mental issues and coordination theories, between micro and macro issues.**

- Mutual representations
- Coordination models
- Organisations
- Methodologies

**Multi-agent systems are in the near future what object oriented systems are today: a set of well defined techniques**

- Multi-Agent Oriented Programming
- Testbeds and Benchmarks
- Standards
- Available industrial platforms

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## **Evolution of Agents and Multi-Agent Systems**

**Robotics Agents**  
**Mobile Agents**  
**Software Agents**  
**Interface Agents**  
**WWW Agents**

...

**Artificial Intelligence**  
**Telecommunications**  
**Software Engineering**  
**HC Interfaces**  
**Internet Computing**

**MAS assuming Closed Environments**  
**MAS integrating Open Environments**  
**MAS including Human Agents (CSCW, ITS)**

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## **THE MAGMA GROUP**

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## **MAGMA : Project in 00-01**

### **Main Axes (Stream 98-02)**

- **Development of the MAGMA Method**
- **Interactions (Approach - Models - Tools)**

### **Approach**

- **A E I O, Emergence**, Recursion
- Domains, **Problems**

### **Models**

- **Agents**, Environments, **Interactions**, **Organisations**
- **Emergence**, Recursion

### **Tools**

- Programming, **Platform**

### **Applications**

- Information Systems
- **Mediation Systems**
- **Autonomous Systems**

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## **MAGMA : Applications in 00-01**

### **Information Systems**

- **Cartographic Generalisation**
  - ✓ AGENT (EU ESPRIT)
- Spatio-Temporal Reasoning

### **Mediation Systems**

- **Distant Learning**
  - ✓ Baghera (academic IMAG)
- **Virtual Reality**
  - ✓ Deuxième Monde (industrial Canal+)

### **Autonomous Systems**

- **Autonomous Robots**
  - ✓ Robocup (academic project)
- Citizen Agents

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## MAGMA : People in 00-01

Staff	Y. Demazeau	CNRS	approach, organisations
	H. Fiorino	UJF	agents, interactions
	JL. Koning	INPG	interactions, models
	M. Occhetto	UPMF	recursion, approach
	S. Pesty	UPMF	interactions, agents
Post Doctoral	C. Baeijs	INPG	organisations, approach
PhD students	<i>E. Fianyo - 4</i>	<i>UPD</i>	<i>dynamics, application</i>
	G. Chicoisne - 3	INPG	interactions, agents
	K. Fernandes - 3	UJF	approach, recursion
	M.-P. Huget - 3	UPD	interactions, models
	P.-M. Ricordel - 3	INPG	tools, programming
	J.L. Tavares - 2	UJF	interactions, applications
	C. Webber - 2	INPG	interactions, applications
	R. Frozza - 2	UFRGS	interactions, applications
	I. Romero - 1	UJF	interactions, models
	A. Zunino - 1	UJF	<i>interactions, applications</i>
MSc students	Ph. Couspeyre	INPG	approach, applications

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## Future MAGMA research

### Multi-Agent Oriented Programming

- The Volcano platform
- Domains and Problems
- Applications : The Citizen Agents and AgentCities projects

### Emotional and Conversational Agents

- Dialogism
- Emotional agents
- Applications : The PARI and Baghera projects

### Real-Time Coordination and Planning

- MAS-centered Planning
- MAS-centered Learning
- Applications : The AgentCities and PARI projects

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